Algrthm

Sqnc

Rpttn

Slctn

Lp

Whl Lp

Cmmnt

Vrbl

MicroBits have a number of **sensors** on them. These can be used to measure things.

Sensors work best when combined with **variables**.

- One of the sensors is the **accelerometer**.
- This measures speed, movement, direction and how the micro:bit is tilted.
- It can be used to warn the sailor if the boat is in danger of capsizing...

accelerometer.get_x()

Using the **Python Editor**...

Write a program to measure the tilt of the micro:bit

Challenges:

- 1. how sensitive is the tilt reading?
- 2. far does the reading go?
- 3. what happens when it goes the other way?
- 4. what is a sensible reading to alert the user at?
- 5. can you measure the backwards/forwards tilt?

REPEAT FOREVER

SET reading TO accelerometer.getx()

IF tilt is too much

DISPLAY something

ELSE

DISPLAY "-"

REPEAT FOREVER SET reading TO accelerometer.getx() IF reading > 20: DISPLAY "X" ELSE DISPLAY "-"

REPEAT FOREVER SET reading TO accelerometer.getx() IF reading > 20: DISPLAY "R" ELSE IF reading < ???: DISPLAY "L" ELSE DISPLAY "-"

```
# Add your Python code here. E.g.
from microbit import *
while True:
    reading = accelerometer.get_x()
    if reading > 20:
        display.show("R")
    elif reading < -20:
        display.show("∟")
    else:
        display.show("-")
```